

Chapter 1

Linear Systems

1.1 Linear Map of the Interval

1. $x' = \lambda x$

- $0 < \lambda < 1$
- $1 < \lambda < \infty$
- $\lambda = +1$
- $\lambda = -1$
- $-1 < \lambda < 0$
- $-\infty < \lambda < -1$

2. Fixed points: stable and unstable

3. Stability: Dynamical and structural

4. $x' = f(x; \lambda)$

5. State space

6. Control parameters

7. Affine map: $x' = ax + b$

1.1.1 Cobweb Diagrams

1.1.2 Fixed Points

1.1.3 Lyapunov Exponent

1.1.4 State Variables - Control Parameters

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1.1.5 Dynamical Stability**1.1.6 Structural Stability****1.2 One Dimensional Linear Flows**

$$\frac{dx}{dt} = \lambda x$$

- $0 < \lambda < \infty$
- $\lambda = 0$
- $-\infty < \lambda < 0$

1.2.1 Simple (Canonical) Forms**1.2.2 Fixed Points****1.2.3 Lyapunov Exponent****1.2.4 Dynamical Stability****1.2.5 Structural Stability****1.3 Linear Map of R^2** **1.3.1 Description by Matrices****1.3.2 Lyapunov Exponents****1.3.3 Fibonacci Sequences****1.3.4 Partition of Control Parameter Space: Tr and Det****1.3.5 Other Two-Dimensional Spaces**

$R^1 \times S^1$, $S^1 \times S^1$, S^2 , ..., Klein bottles, real projective spaces, stuff with handles, tori.

1.4 Two Dimensional Linear Flows

$$\frac{d}{dt} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

Stability plot in Tr, Det space.

1.4.1 Simple Canonical Forms**1.4.2 Lyapunov Exponent****1.4.3 Dynamical Stability****1.5 Algorithms****1.5.1 The First Algorithm**

$$x_{n+1} = \frac{1}{2} \left(x_n + \frac{3}{x_n} \right) \rightarrow \sqrt{3}$$

Newton's method

Cube roots of +1: Basins of Attraction

1.6 Two Simplest Nonlinear Equations

1. $\frac{dx}{dt} = \lambda x(1-x)$
2. $x' = \lambda x(1-x)$

1.7 Basins of Attraction

For square root algorithm

For cube root algorithm

For

$$\left(\frac{1}{x} + \frac{1}{1-x} + \frac{1}{x-2} \right) dx = \lambda dt$$

For potentials

1.8 Catastrophe Theory

Morse potentials, degenerate critical points, magic transformations, families of catastrophes, A_1 (normal critical p[oint]), A_2 (fold), A_3 cusp, A_4 butterfly, etc.

Saddle-node bifurcations, symmetry-breaking bifurcations, period-doubling bifurcations.

Germ and unfoldings.